

**TRINITY COLLEGE FOR WOMEN** NAMAKKAL **Department of Mathematics** PARTIAL DIFFERENTIAL **EQUATIONS** (Part-II) **19PMA08-ODD Semester Presented by** Dr.R.MALARVIZHI Assistant Professor & HOD-PG, **Department of Mathematics** http://www.trinitycollegenkl.edu.in/

## Explain canonical forms of Elliptic, Hyperbolic, and Parbolic :

**Reduce the PDE** 

 $R_r + S_s + T_t + f(x,y,z,p,q) = 0$  ------ (1) to a canonical form we apply the transformation.

 $\xi = \xi (x,y)$ ,  $\eta = \eta (x,y)$  ------ (2)

such that, the function  $\xi$  and  $\eta$  are continuously differentiable and the jacobian

$$J = \frac{\partial (\xi, \eta)}{\partial (x, y)} = \begin{vmatrix} \xi_x & \xi_y \\ \eta_x & \eta_y \end{vmatrix} = \xi_x \eta_y - \eta_x \xi_y \neq 0 \quad \dots \quad (3)$$
  
in the domain ' $\Omega$ ', where equation (1) holds, Now we have,  
$$P = \frac{\partial z}{\partial x} = \frac{\partial z}{\partial \xi} \cdot \frac{\partial \xi}{\partial x} + \frac{\partial z}{\partial \eta} \cdot \frac{\partial \eta}{\partial x}$$

 $\mathbf{P} = \mathbf{Z}_{\boldsymbol{\xi}} \cdot \boldsymbol{\xi}_{\mathbf{x}} + \mathbf{Z}_{\boldsymbol{\eta}} \cdot \boldsymbol{\eta}_{\mathbf{x}}$  $\mathbf{p} = \xi \mathbf{x} \cdot \mathbf{Z} \xi + \eta_{\mathbf{x}} + \mathbf{Z}_n$  $\mathbf{q} = \boldsymbol{\xi}_{\mathrm{y}_{\mathrm{o}}} \mathbf{Z}_{\boldsymbol{\xi}} + \boldsymbol{\eta}_{\mathrm{y}} + \mathbf{Z}\boldsymbol{\eta}$  $\mathbf{r} = \frac{\partial^2 z}{\partial x^2} = \frac{\partial}{\partial x} \left( \frac{\partial z}{\partial x} \right)$  $\mathbf{r} = \frac{\partial}{\partial r} \left( \xi_{\mathrm{x}} \cdot \mathbf{Z}_{\xi} + \eta_{\mathrm{x}} \cdot \mathbf{Z}_{\eta} \right)^{T}$  $\mathbf{r} = \frac{\partial}{\partial \xi} \left[ \xi_{x} \cdot Z_{\xi} + \eta_{x} \cdot Z_{\eta} \right] \frac{\partial \xi}{\partial \xi} + \frac{\partial}{\partial \xi} \left[ \xi_{x} \cdot Z_{\xi} + \eta_{x} \cdot Z_{\eta} \right] \frac{\partial \eta}{\partial x}$  $\mathbf{r} = \xi_x^2 \mathbf{Z}_{\boldsymbol{\xi}\boldsymbol{\xi}} + \xi_{xx} \mathbf{Z}_{\boldsymbol{\xi}} + 2 \xi_x^{\partial x} \mathbf{\eta}_x \mathbf{Z}_{\boldsymbol{\eta}\boldsymbol{\xi}} + \eta_{xx} \mathbf{Z}_{\boldsymbol{\eta}} + \eta_x^2 \mathbf{Z}_{\boldsymbol{\eta}\boldsymbol{\eta}}$ Simlarly,

 $t = \xi_{y}^{2} Z_{\xi\xi} + \xi_{yy} Z_{\xi} + 2 \xi_{y} \eta_{y} Z_{\eta\xi} + \eta_{yy}^{2} Z_{\eta} + \eta_{y}^{2} Z_{\eta\eta}$   $s = \xi_{x} \xi_{x} Z_{\xi\xi} + \eta_{x} \eta_{y} Z_{\eta\eta} + \xi_{x} \eta_{y} Z_{\eta\xi} + \xi_{y} \eta_{x} Z_{\eta\xi} + \xi_{x} \eta_{y} Z_{\xi} + \eta_{x} \eta_{y} Z_{\eta}$ Substitute these values of p,q,r,s,t in (1) we get  $A(\xi_{x}, \xi_{y}) Z_{\xi\xi} + 2B(\xi_{x}, \xi_{x}, \eta_{x}, \eta_{y}) Z_{\eta\xi} + A(\eta_{x}, \eta_{y}) Z_{\eta\eta}$   $+ F(\xi, \eta, Z, Z_{\xi}, Z_{\eta}) = 0 \quad ----- \quad (4)$ Where,

 $A(U,V) = Ru^2 + Suv + Tv^2$ 

2B ( $u_1$ ,  $u_2$ ,  $v_1$ ,  $v_2$ ) = 2R $u_1u_2$  + S( $u_1v_2$  +  $u_2v_1$ ) + 2T $v_1v_2$ Now it can be easily verified that, 2B<sup>2</sup>( $\xi_x$ ,  $\xi_y$ ,  $\eta_x$ ,  $\eta_y$ ) - A( $\xi_x$ ,  $\xi_y$ ) A( $\eta_x$ ,  $\eta_y$ ) = (S<sup>2</sup> - 4RT) J ----- (5) where J is given by (3) Case (i): S<sup>2</sup> - 4RT > 0

Under the condition  $S^2 - 4RT > 0$ , the equation  $R\lambda^2 + S\lambda + T = 0$  has real and distinct roots.

Let these roots be  $\lambda_1$  and  $\lambda_2$ 

We choose  $\,\xi\,\,and\,\eta\,\,such\,\,that\,\,\xi_{\,x}\,=\,\lambda_{1}\xi_{y}$  ,  $\eta_{x}\,=\,\lambda_{2}\,\eta_{y}$  Now,

 $\xi_{x} = \lambda_{1}\xi_{y} - \dots - (6)$   $\xi_{x} - \lambda_{1}\xi_{y} = 0 \text{ being a first order lineat PDE.}$ we've,  $\frac{dx}{1} = \frac{dy}{-\lambda_{1}} = \frac{d\xi}{0}$ Therefore,  $d\xi = 0$   $\xi = \text{constant}$  $\frac{dx}{1} = \frac{dy}{-\lambda_{1}}$   $\frac{dx}{1} = \frac{dy}{-\lambda_1}$ 

Let the solution of these equations be given by,  $f_1(x,y) = constant$  $f_2(x,y) = constant$ Thus we get,  $\xi = f_1(x,y)$  and  $\eta = f_2(x,y)$  ------ (8) Now,  $A(\xi_x,\xi_v) = R\xi_x^2 + S\xi_x\xi_v + T\xi_v^2$  $= R\lambda_1^2 \xi_v^2 + S\lambda_1 \xi_v \xi_v + T\xi_v^2$  $= \xi_v^2(0)$  [since,  $\lambda_1$  is a root of  $R\lambda^2 + S\lambda + T = 0$ ]  $A(\xi_x,\xi_v)=0$ 

Similarly,

$$\begin{split} A(\eta_x, \eta_y) &= 0 \quad [since, \lambda_2 \text{ is a root of } R\lambda^2 + S\lambda + T = 0] \\ B^2 &= (S^2 - 4RT) \text{ J} \neq 0 \end{split}$$

**Equation (4) reduces to** 

 $\mathbf{Z}_{\boldsymbol{\xi}\boldsymbol{\eta}} = \mathbf{g} (\boldsymbol{\xi}, \boldsymbol{\eta}, \mathbf{Z}, \mathbf{Z}_{\boldsymbol{\xi}}, \mathbf{Z}_{\boldsymbol{\eta}})$ 

which is required canonical form for the hyperbolic PDE. Case (ii) :

Then  $R\lambda^2 \cdot S^{2} \cdot 4RT = 0$  equal roots. i.e)  $\lambda_1 = \lambda_2 = \lambda$  (say) we choose  $\xi = f_1(x,y)$ ,  $f_1(x,y) = \text{constant}$  is a solution of  $\frac{dy}{dx} + \lambda(x,y) = 0$ where  $\frac{A(\xi_x, \xi_y) = 0}{S^2 - 4RT = 0}$ Therefore equation (5) implies, B = 0

## However,

 $\begin{array}{l} A(\eta_x,\eta_y) \neq \mathbf{0} \\ \\ \text{Otherwise } \eta \text{ will depend upon `\xi' using } A = B = 0 \text{ in (4),we get} \\ \\ Z_{\eta\eta} = g \; (\; \xi,\eta,Z,Z_{\xi},Z_{\eta}) \\ \\ \text{which is the required canonical form for the parabolic PDE} \\ \\ \\ \text{Case(iii) :} \end{array}$ 

S<sup>2</sup> - 4RT < 0

In this case the roots of  $R\lambda^2+S\lambda+T=0$  are imaginary. Therefore,  $\xi$  and  $\eta$  will be complex. Let  $\xi = \alpha + i\beta$  $\eta = \alpha - i\beta$  where,  $\alpha$ ,  $\beta$  are equal  $\alpha = 1/2 (\xi + \eta)$   $\beta = 1/2(\eta - \xi)$ with this transformation we have

 $\mathbf{Z}_{\xi\eta} = \frac{1}{4} \left( \mathbf{Z}_{\alpha\alpha} + \mathbf{Z}_{\beta\beta} \right)$ 

and proceeding on the similar lines as on case (i) we get,

 $Z_{\alpha\alpha} + Z_{\beta\beta} = \Phi(\alpha, \beta, Z, Z_{\alpha}, Z_{\beta})$ which is the required canonical form for the Elliptical PDE.

## Conclusion :

i) If S<sup>2</sup> - 4RT < 0, then it is Elliptic.</li>
ii) If S<sup>2</sup> - 4RT = 0, then it is Parabolic.
iii) If S<sup>2</sup> - 4RT > 0, then it is Hyperbolic.

## THANK YOU

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